Symmetry in Particle Physics, Problem Sheet 2

- 1. Show that a representation D of a Lie group is unitary if and only if the generators X_a are hermitian.
- 2. Consider the elements of an algebra X_a , with commutator

$$[X_a, X_b] = i f_{abc} X_c \,.$$

Show that if this algebra generates a unitary representation, then the structure constants f_{abc} are real.

3. Analytic functions of operators (matrices) A are defined via their Taylor expansion about A = 0. Consider the function

$$g(x) = \exp(xA) B \, \exp(-xA) \,,$$

where x is real and A, B are operators.

- (a) Compute the derivatives $d^n g(x)/dx^n$ for integer *n*, and simplify the result using the convention [A, B] = AB BA.
- (b) Using the result of part (a), show that

$$e^{A} B e^{-A} = B + [A, B] + \frac{1}{2!} [A, [A, B]] + \frac{1}{3!} [A, [A, [A, B]]] + \dots$$

- 4. We want to prove the Baker-Campbell-Hausdorff formula in a situation where the operators (matrices) A, B have the property [A, [A, B]] = 0 = [B, [A, B]].
 - (a) Show that $[A^n, B] = nA^{n-1}[A, B]$ for integer $n \ge 1$.
 - (b) Use the above to show that, for analytic functions f(x),

$$[f(A), B] = f'(A) [A, B].$$

Show then that, if x is a c-number (i.e. a real or complex number), we have

$$[B, \exp(-Ax)] = \exp(-Ax)[A, B]x$$

(c) Consider the function $f(x) = \exp(xA)\exp(xB)$ and, using the result of part (b), show that it obeys the differential equation

$$\frac{df(x)}{dx} = (A + B + [A, B]x) f(x).$$

Compute f(x) by solving the above equation with an appropriate initial condition, and use the result to deduce the Baker-Campbell-Hausdorff formula for this case, i.e.

$$e^{A}e^{B} = e^{A+B}e^{\frac{1}{2}[A,B]}$$

Note: f(x) is not in general invertible, so the equation has to be solved using an ansatz.

- 5. Compute the dimension of the group SU(N).
- 6. Consider the Pauli matrices

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \ \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \ \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

(a) Using the conventions [A, B] = AB - BA, $\{A, B\} = AB + BA$, show that the matrices $\frac{\sigma_i}{2}$ are a two-dimensional representation of the SU(2) algebra,

$$\left[\frac{\sigma_i}{2}, \frac{\sigma_j}{2}\right] = i \,\epsilon_{ijk} \,\frac{\sigma_k}{2} \,,$$

and $\epsilon_{123} = +1$. Show also that

$$\left\{\frac{\sigma_i}{2}, \frac{\sigma_j}{2}\right\} = \frac{\sigma_0}{2} \,\,\delta_{ij}\,,$$

with $\sigma_0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ denoting the two-dimensional identity matrix.

(b) Consider the SU(2) group element $G = \exp(\frac{i}{2}\theta_3\sigma_3)$ with parameter θ_3 . Show by explicit computation that

$$\exp\left(\frac{i\theta_3}{2}\sigma_3\right) = \sigma_0 \cdot \cos(\theta_3/2) + i\,\sigma_3\,\cdot\sin(\theta_3/2)$$

(c) A general SU(2) group element is written as $G = \exp(\frac{i}{2}\theta_k\sigma_k)$ with parameters θ_k . Show, either by explicit computation or with the help of part (b) and symmetry arguments, that

$$\exp\left(\frac{i\theta_k}{2}\sigma_k\right) = \sigma_0 \cdot \cos(\theta/2) + i\left(\hat{\theta}_k\sigma_k\right) \cdot \sin(\theta/2) \,.$$

Here, $\hat{\theta}_k = \theta_k/\theta$ is the unit vector in the θ_k -direction, and $\theta \equiv |\theta|$. Perform the above group transformation using $\theta = 2\pi$ and $\theta = 4\pi$, respectively. What does this tell us about the relation between SU(2) and SO(3)?

7. The spin-1 representation of SU(2) with generators T_1, T_2, T_3 satisfying $[T_i, T_j] = i \epsilon_{ijk} T_k$ reads

$$T_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, \quad T_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix}, \quad T_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}.$$

Consider the corresponding SU(2) group element $\Omega(\theta_i) = \exp(i\theta_i T_i)$ with parameters $\theta_i \ i = 1, 2, 3$. Here $\hat{\theta}_i = \theta_i / |\theta|$ is the unit vector in the θ_i -direction, and $\theta \equiv |\theta|$.

- (a) Show with a direct computation, or with symmetry arguments, that the matrix $\hat{\theta}_i T_i$ must have eigenvalues ± 1 and 0.
- (b) Use the result of part (a) to show that the square $(\hat{\theta}_i T_i)^2$ is a projection operator (i.e. $(\hat{\theta}_i T_i)^4 = (\hat{\theta}_i T_i)^2$) and $(\hat{\theta}_i T_i)^3 = \hat{\theta}_i T_i$

$$(\theta_i T_i)^{\mathfrak{s}} = \theta_i T_i$$

Show then that $\Omega(\theta_i)$ is the 3×3 matrix

$$\Omega(\theta_i) = \mathbb{1} + i \left(\hat{\theta}_i T_i \right) \cdot \sin \theta + (\hat{\theta}_i T_i)^2 \cdot \left(\cos \theta - 1 \right) \,,$$

where 1 is the 3-dimensional identity matrix.

8. Given a three-dimensional vector $\vec{v} = (v_1, v_2, v_3)$, we construct the 2 × 2 matrix $\bar{v} = v_i \sigma_i$, with $\sigma_i, i = 1, 2, 3$ the three Pauli matrices, as follows

$$\bar{v} = \left(\begin{array}{cc} v_3 & v_1 - iv_2 \\ v_1 + iv_2 & -v_3 \end{array}\right)$$

(a) Show that $\vec{v}^2 = -\det(\vec{v})$. Then show that, for any two vectors \vec{v} and \vec{w} ,

$$\vec{v} \cdot \vec{w} = \frac{1}{4} \left[\det(\bar{v} - \bar{w}) - \det(\bar{v} + \bar{w}) \right] \,.$$

(b) Using the properties of Pauli matrices, show that, for any matrix $U \in SU(2)$, the matrix

$$\bar{v}' = U \,\bar{v} \,U^{\dagger} \,,$$

can be written in the form $\bar{v}' = v'_i \sigma_i$, where

$$v'_i = \Omega_{ij} v_j, \qquad \Omega_{ij} = \frac{1}{2} \operatorname{Tr} \left[\sigma_i U \sigma_j U^{\dagger} \right]$$

Hint. Any 2×2 complex matrix M can be written as $M = M_0 \mathbb{1} + M_i \sigma_i$.

(c) Show that Ω is an orthogonal transformation, i.e. if $\vec{v}' = \Omega \vec{v}$ and $\vec{w}' = \Omega \vec{w}$, then $\vec{v}' \cdot \vec{w}' = \vec{v} \cdot \vec{w}$.