

# Nonlocal geometric flows

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# A classical geometric evolution

Motion by mean curvature:  $t \mapsto E_t \subset \mathbb{R}^d$

$$V = H_{\partial E_t} \quad \text{su } \partial E_t \quad (\text{MCM})$$

$V$  is the normal velocity of  $\partial E_t$

$H_{\partial E_t}$  is the mean curvature of  $\partial E_t$ .

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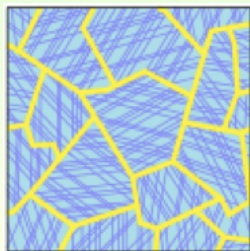
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Proposed by Mullins (1956) to describe the evolution of crystalline grains:



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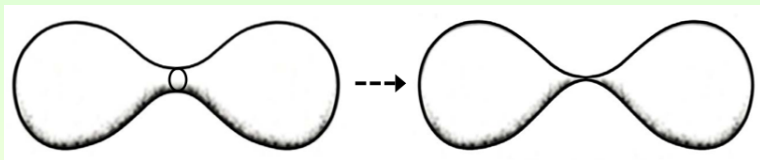


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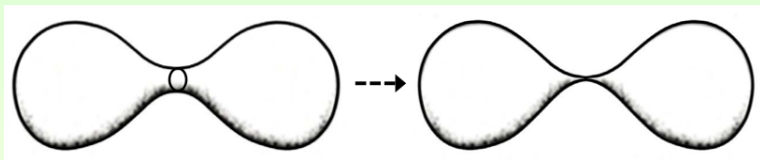


Figure : An example of pinching singularity (Grayson '89).

Question: how to define a global-in-time solution?

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- ▶ Proposed by **Osher & Sethian (1988)** for numerical purposes, as a method to deal with **topological changes**.
- ▶ **Global existence** and **uniqueness** for (EqIL) has been established in **Evans & Spruck (1991)** and **Chen-Giga-Goto (1991)** within the formalism of **viscosity solutions**.

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- One defines a discrete-in-time evolution by iteration:

$$E_{n+1} \in \operatorname{argmin} \left( \operatorname{Per}(F) + \frac{1}{\tau} \int_{F \Delta E_{n-1}} d(x, \partial E_{n-1}) dx \right)$$

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$J$  is **submodular**  $\iff \tilde{J}$  is **convex** (Chambolle, Giacomini, Lussardi 2010).

# Generalized curvatures

## Definition

We say that  $\kappa(\cdot, E)$  is the *curvature of  $\partial E$*  associated with  $J$  if per any smooth family of diffeomorphisms  $(\Phi_\varepsilon)_\varepsilon$ , with  $\Phi_0 = Id$ , one has

$$\frac{d}{d\varepsilon} J(\Phi_\varepsilon(E)) \Big|_{\varepsilon=0} = \int_{\partial E} \kappa(x, E) X(x) \cdot \nu^E(x) d\mathcal{H}^{N-1}(x).$$

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- **Non degeneracy:**  $\inf_{\rho>0} \min_{x \in \partial B_\rho} \kappa(x, B_\rho) > -\infty$ .

# Consequences of convexity

## Lemma (Subgradient inequalities)

Let  $E \in C^2$  and  $x \in \partial E$ . Then

$$J(E) - J(E \setminus W_n) \leq |W_n \cap E|(\kappa(x, E) + o(1))$$

and

$$J(E \cup W_n) - J(E) \geq |W_n \setminus E|(\kappa(x, E) + o(1))$$

if  $W_n \rightarrow \{x\}$  in the Hausdorff sense.

# Consequences of convexity

## Lemma (Monotonicity)

*Let  $E, F \in C^2$  with  $E \subseteq F$  and let  $x \in \partial F \cap \partial E$ . Then*

$$\kappa(x, F) \leq \kappa(x, E).$$

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  - ▶ Representation via super-level sets



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- The strong formulation of (GMC) becomes meaningless when singularities appear
- Need for a weak formulation:
  - ▶ Representation via super-level sets
  - ▶ Viscosity formulation of the corresponding equation

# Level set formulation

Representing  $E(0) := \{u_0 \geq 0\}$ , one is led to the Cauchy problem:

$$\begin{cases} u_t(x, t) + |Du(x, t)|\kappa(x, \{y : u(y, t) \geq u(x, t)\}) = 0 \\ u(0, \cdot) = u_0. \end{cases}$$

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- **Weak formulation:** The curvature  $\kappa$  is defined only on regular sets. We consider **viscosity solutions**.
- **Functional setting:** Evolution of sets with **compact boundary**. Therefore,  $u$  and the test functions are constant outside a compact set.

# Definition of viscosity solution

## Definition

A continuous function  $u : \mathbb{R}^d \times [0, T] \rightarrow \mathbb{R}$  is a *viscosity subsolution* if  $u(0, \cdot) \leq u_0$ , and for any test function  $\varphi$  of class  $C^2$  s.t.  $u - \varphi$  has a *maximum* at  $z := (x, t)$ , one has

$$\varphi_t(z) + |D\varphi(z)| \kappa(x, \{y : \varphi(y, t) \geq \varphi(z)\}) \leq 0,$$

if the level set  $\{\varphi(\cdot, t) = \varphi(z)\}$  is not critical, and  $\varphi_t(z) \leq 0$  if  $D\varphi(z) = 0$  (and  $\varphi$  “flat enough” at  $z$ ).

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- Extension of  $\kappa$  to non-regular sets by **semicontinuity**.
- **Perron's Method** extends to this setting

# The minimizing movements scheme

For any fixed **time step**  $h > 0$ , let  $T_h E$  be the **minimal solution** to

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Lemma (Discrete Comparison Principle)

$$E \subseteq E' \implies T_h E \subseteq T_h E'.$$

# Time-discrete evolutions

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- Let  $u_0 \in BUC(\mathbb{R}^d)$ , constant outside a compact set. We define

$$u_h(x, t) := (T_h)^{[\frac{t}{h}]} u_0.$$

- One can show that  $u_h$  is still **constant outside a compact (spacial) set**.

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$$T_h u(x) := \sup\{s : x \in T_h\{u \geq s\}\}.$$

- Let  $u_0 \in BUC(\mathbb{R}^d)$ , constant outside a compact set. We define

$$u_h(x, t) := (T_h)^{[\frac{t}{h}]} u_0.$$

- One can show that  $u_h$  is still **constant outside a compact (spacial) set**.

# Equicontinuity

## Lemma

*For every  $\varepsilon > 0$  there exists  $\tau > 0$  s.t. if  $h > 0$  is small enough,  $|x - y| \leq \tau$  and  $|i/h - j/h| \leq \tau$  with  $i, j \in \mathbb{N}$ , then  $|u_h(i/h, x) - u_h(j/h, y)| \leq \varepsilon$ .*



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- **Equicontinuity in time:** follows from discrete comparison principle + estimate on how fast balls shrink.

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- **Non degeneracy:**  $\inf_{\rho>0} \min_{x \in \partial B_\rho} \kappa(x, B_\rho) > -\infty$ .

# Uniqueness

We consider two different hypotheses:

(FO): (*First order curvatures*) Let  $\Sigma \in \mathcal{C}^{1,1}$  and  $x \in \partial\Sigma$ . Then

$$\begin{aligned} \sup \left\{ \kappa(x, F) : F \in C^2, F \supseteq \Sigma, x \in \partial F \right\} \\ = \inf \left\{ \kappa(x, F) : F \in C^2, \mathring{F} \subseteq \Sigma, x \in \partial F \right\}. \end{aligned}$$



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(UC) (*Uniform  $\mathcal{C}^2$ -continuity*) Given  $r > 0$ , there exists  $\omega_r$  such that:

For every  $E \in \mathcal{C}^2$ ,  $x \in \partial E$  satisfying a **ball condition of radius  $r$**  at  $x$  and for every diffeomorphisms  $\Phi : \mathbb{R}^d \rightarrow \mathbb{R}^d$  of class  $\mathcal{C}^2$

$$|\kappa(x, E) - \kappa(\Phi(x), \Phi(E))| \leq \omega_r(\|\Phi - Id\|_{\mathcal{C}^2}).$$

# Uniqueness

Theorem (Chambolle-M.-Ponsiglione, ARMA 2015)

Assume that (FO) or (UC) hold. Then

$$\begin{cases} u_t(x, t) + |Du(x, t)|\kappa(x, \{y : u(y, t) \geq u(x, t)\}) = 0 \\ u(0, \cdot) = u_0. \end{cases}$$

admits a *unique* viscosity solution.

# Examples and applications: the fractional mean curvature flow

- For  $\alpha \in (0, 1)$  consider the **fractional perimeter**

$$J^\alpha(E) := \int \int_{\mathbb{R}^d \times \mathbb{R}^d} \frac{|\chi_E(x) - \chi_E(y)|}{|x - y|^{N+\alpha}} dx dy = [\chi_E]_{H^{\frac{\alpha}{2}}}^2.$$

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- Our approximation is new and alternative to **Caffarelli&Souganidis ARMA (2010)**.

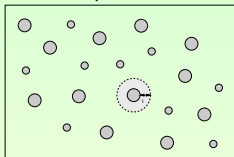
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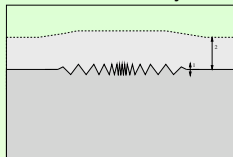
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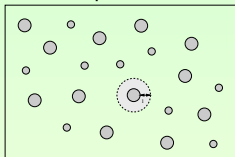
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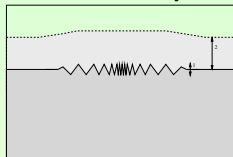
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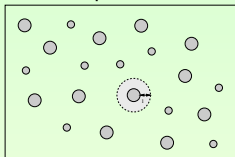


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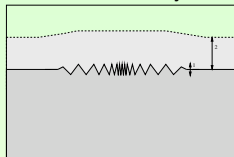
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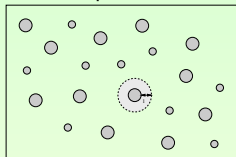
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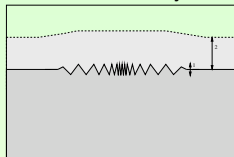
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- If  $\phi$  is smooth, then (AMC) falls within the previous theory

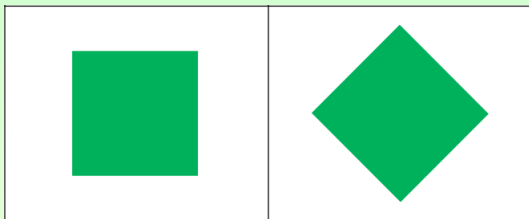
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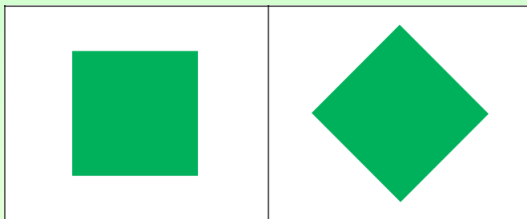
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The unit ball  $B_\phi$

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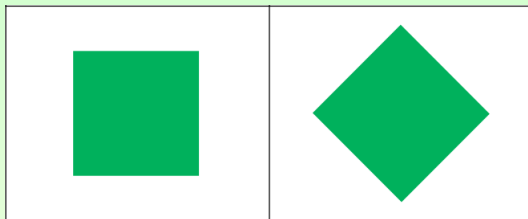


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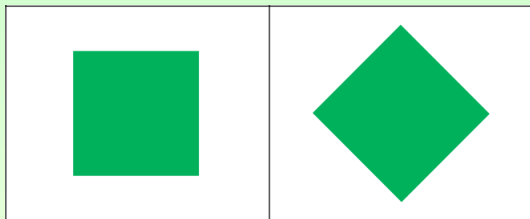


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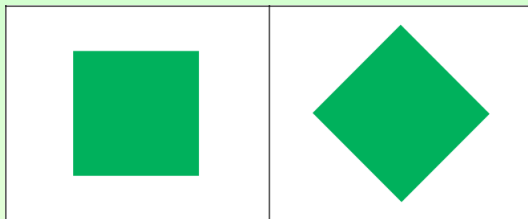
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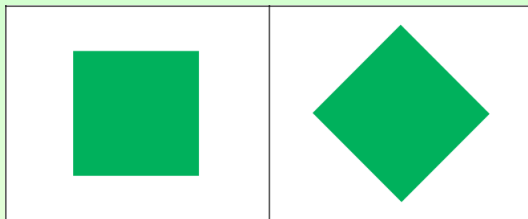


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  - ▶ **Convex initial data**: Caselles & Chambolle (2006) and Bellettini, Caselles, Chambolle & Novaga (2006)
  - ▶ **Polyhedral initial data**: Giga, Gurtin & Matias (1998)
  - ▶ General initial data, but for a **specific cylindrical anisotropy**: Giga, Giga & Pozar (2014)
  - ▶ Global-in-time solution via ATW scheme; **no general comparison principle** known so far.

# Latest developments

## New result (Chambolle-M.-Ponsiglione 2015)

Let  $\phi$  be any crystalline anisotropy. Then, the crystalline mean curvature equation

$$V = -\phi(\nu^{E(t)})\kappa_{\phi}^{E(t)}$$

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- Our result holds only for the “natural” mobility  $m = \phi$ .

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$$\partial_t d^c \geq \text{div}(\nabla \phi(\nabla d^c)) \quad \text{in } \{d^c > 0\}. \quad (2)$$

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**Open Problem**: the general mobility case (future investigations).

THE END

THANK YOU!!