

# Mathematical Concepts (G6012)

## Lecture 12

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# Matrix multiplication

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \cdot \begin{pmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{pmatrix} =$$

$$\begin{pmatrix} a_{11}b_{11} + a_{12}b_{21} + a_{13}b_{31} & a_{11}b_{12} + a_{12}b_{22} + a_{13}b_{32} & a_{11}b_{13} + a_{12}b_{23} + a_{13}b_{33} \\ a_{21}b_{11} + a_{22}b_{21} + a_{23}b_{31} & a_{21}b_{12} + a_{22}b_{22} + a_{23}b_{32} & a_{21}b_{13} + a_{22}b_{23} + a_{23}b_{33} \\ a_{31}b_{11} + a_{32}b_{21} + a_{33}b_{31} & a_{31}b_{12} + a_{32}b_{22} + a_{33}b_{32} & a_{31}b_{13} + a_{32}b_{23} + a_{33}b_{33} \end{pmatrix}$$

The squares illustrate how things combine, analogous for the other fields.

# Properties of Matrix Multiplication

Associativity:  $A \cdot (B \cdot C) = (A \cdot B) \cdot C$

Not commutative (!!!):  $A \cdot B \neq B \cdot A$

Under certain circumstances the Inverse of a matrix exists:

$$A \cdot A^{-1} = \mathbf{1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

So-called “right inverse”

# Non-square matrices

Matrices do not have to be square:

$$A = \begin{pmatrix} -5 & 2 & 1 \\ 0 & 3 & -1 \end{pmatrix} \in \mathcal{M}(2, 3)$$

$$B = \begin{pmatrix} 1 & -1 \\ 0 & 3 \\ 2 & -2 \end{pmatrix} \in \mathcal{M}(3, 2)$$

$$A \cdot B =$$

# Multiplication

$$\begin{pmatrix} \boxed{-5} & \boxed{2} & \boxed{1} \\ 0 & 3 & -1 \end{pmatrix} \begin{pmatrix} \boxed{1} & -1 \\ \boxed{0} & 3 \\ \boxed{2} & -2 \end{pmatrix} = \begin{pmatrix} \boxed{-3} & 9 \\ -2 & 11 \end{pmatrix}$$

What about  $B^*A$  ?

# Matrix transpose

Transposition is the operation where lines and columns are swapped. Or a reflection along the diagonal, if you want:

$$\begin{aligned} A^T = (a_{ij})^T &= \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}^T \\ &= \begin{pmatrix} a_{11} & a_{21} & a_{31} \\ a_{12} & a_{22} & a_{32} \\ a_{13} & a_{23} & a_{33} \end{pmatrix} = (a_{ji}) \end{aligned}$$

# Properties of transposition

- In “component notation” it looks quite minimal:

$$A = (a_{ij}) , \quad B = (b_{ij}) = A^T$$

$$\Rightarrow b_{ij} = a_{ji}$$

- Row vectors become column vectors (and vice versa)
- $m \times n$  matrix becomes a  $n \times m$  matrix

# Scalar product

The scalar product of two vectors is defined as

$$\vec{x} \cdot \vec{y} := \sum_{i=1}^3 x_i y_i \quad \text{also denoted as } \langle \vec{x}, \vec{y} \rangle$$

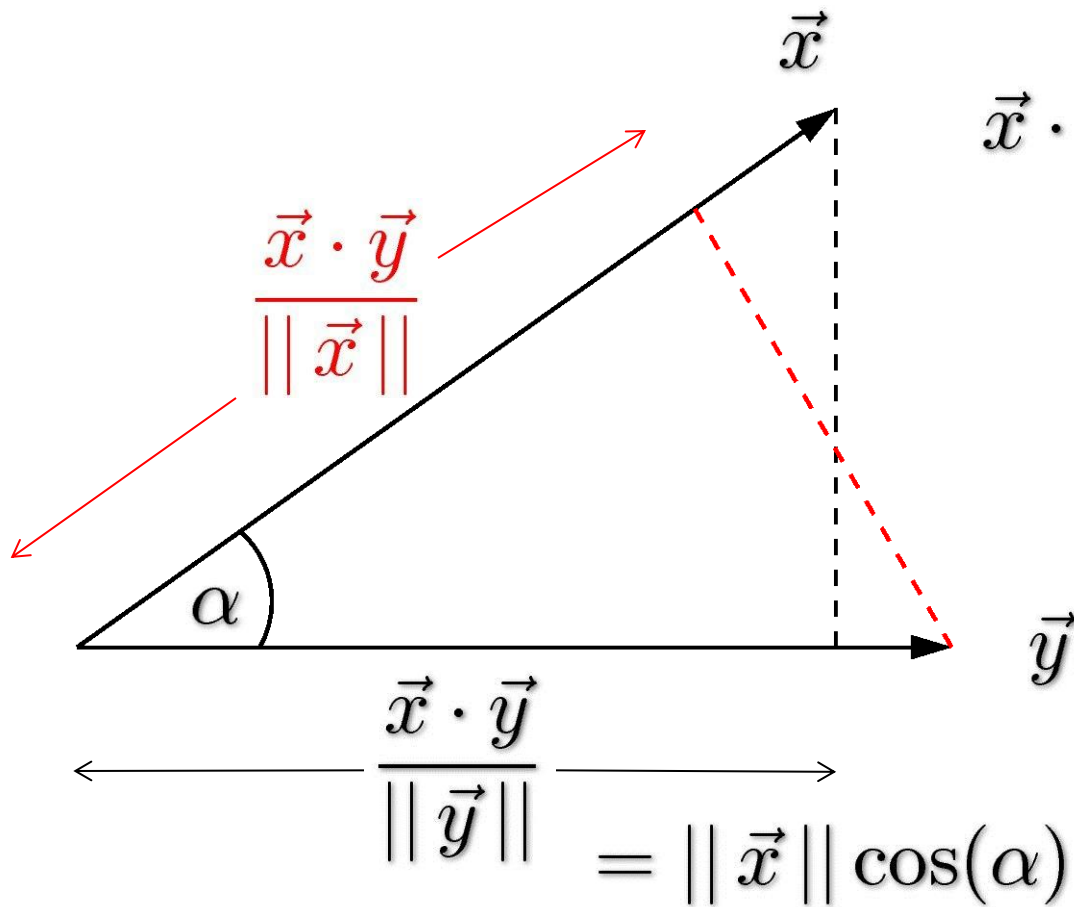
Interpretation: *(in a moment) ...*

It is a special case of Matrix multiplication:

$$\begin{pmatrix} x_1 & x_2 & x_3 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = x_1 y_1 + x_2 y_2 + x_3 y_3$$



# Interpretation of scalar product



$$\vec{x} \cdot \vec{y} = \|\vec{x}\| \|\vec{y}\| \cos(\alpha)$$

Strictly speaking one should write

...

$$\langle \vec{x}, \vec{y} \rangle = \vec{x}^T \cdot \vec{y} \quad \text{for the scalar product.}$$

# Length and distances

- Euclidean norm (length)

$$\vec{x} \in \mathbb{R}^n$$

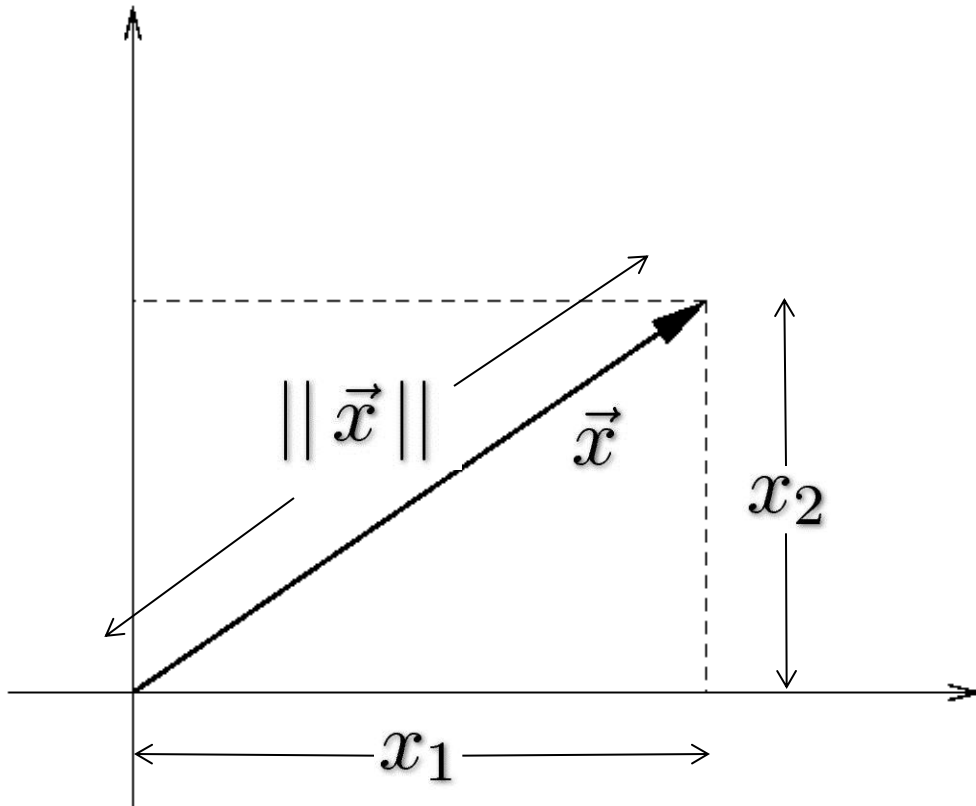
$$\text{Norm of } \vec{x} \text{ is } \|\vec{x}\| := \sqrt{\sum_{i=1}^n x_i^2} = \sqrt{\vec{x} \cdot \vec{x}}$$

It is also called “2-norm”. Why this is our “natural” notion of length: **BB**

Remark: There are many other notions of length

# BB

Why the definition of length matches our intuition for length



$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\|\vec{x}\|^2 = x_1^2 + x_2^2$$

This is the **Pythagorean theorem** (check Wikipedia if never heard of it)

# How does Length become Distance?

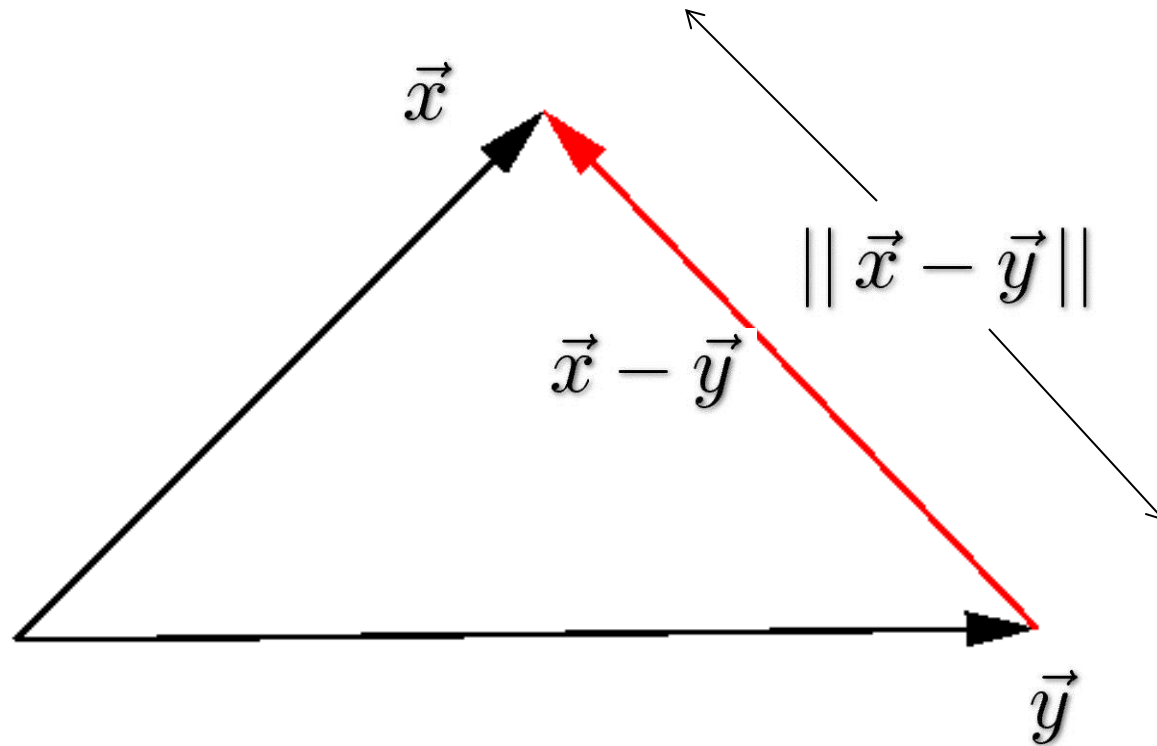
The distance between two vectors (points) is the length of the difference:

$$\vec{x}, \vec{y} \in \mathbb{R}^n$$

$$d(\vec{x}, \vec{y}) = \|\vec{x} - \vec{y}\|$$

It is called **Euclidean distance**. Geometric interpretation: **BB**

# BB Distance



The norm (length)  $\|\vec{x} - \vec{y}\|$  of  $\vec{x} - \vec{y}$  is the distance from  $\vec{x}$  to  $\vec{y}$

# Some properties you would like to know

A norm or distance is always positive or 0.

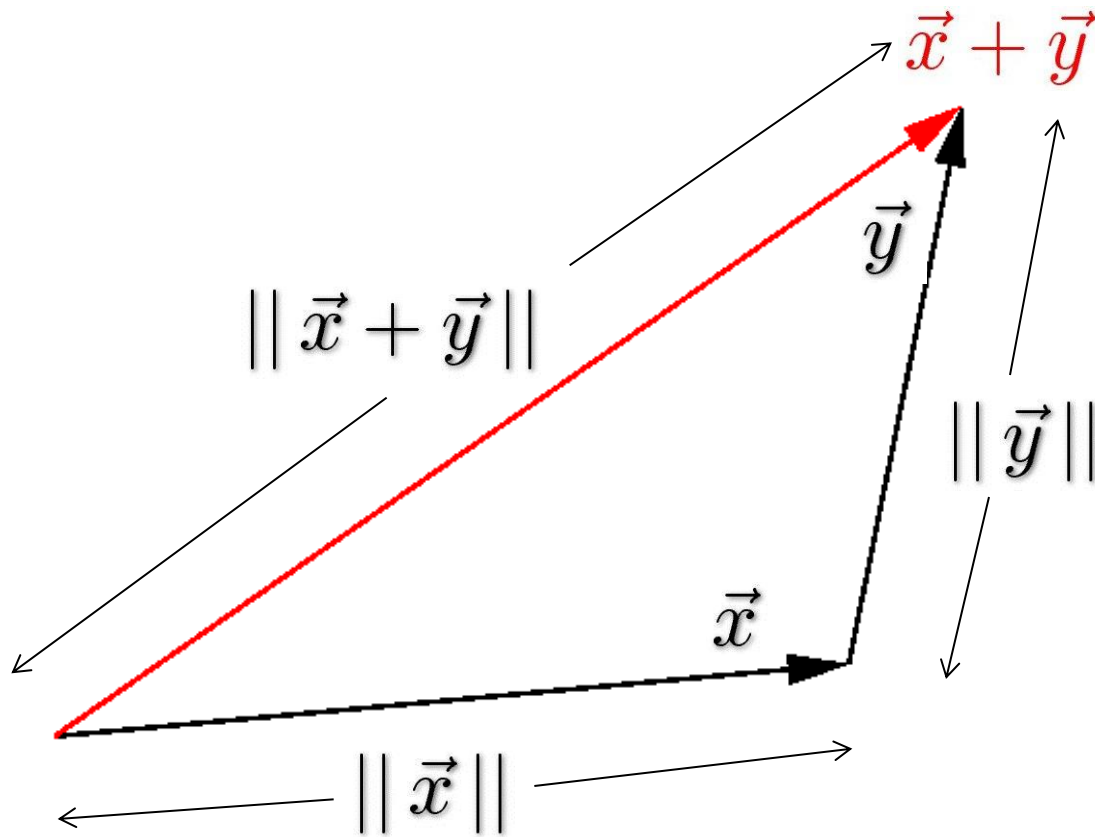
**Scaling vectors:**  $\| a \vec{x} \| = |a| \| \vec{x} \|$

**Triangle inequality:**

$$\| \vec{x} + \vec{y} \| \leq \| \vec{x} \| + \| \vec{y} \|$$

Geometric meaning ... **BB**

# BB Geometric meaning of Triangle Inequality



The triangle inequality means that going along the direct way ( $\|\vec{x} + \vec{y}\|$ ) in a triangle is always shorter than (or equal to) going along the two other sides ( $\|\vec{x}\| + \|\vec{y}\|$ )



# Other common norms

- The 1-norm:  $\|\vec{x}\|_1 = \sum_{i=1}^n |x_i|$

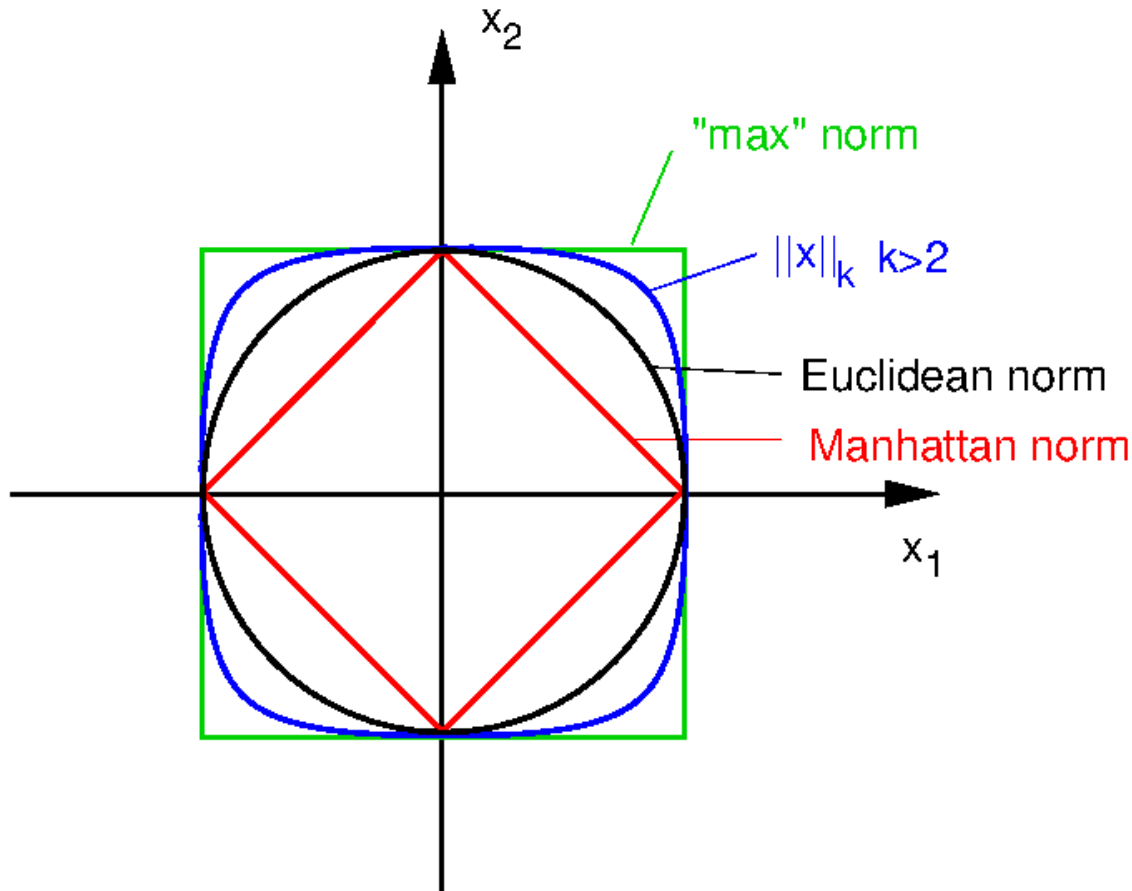
(also called “Manhattan Distance” – why?)

- The n-norm:  $\|\vec{x}\|_k = \left( \sum_{i=1}^n |x_i|^k \right)^{\frac{1}{k}}$

- The  $\infty$  -norm:  $\|\vec{x}\|_\infty = \max_{1 \leq k \leq n} |x_k|$

# BB “isolines”

Lines of points which are the same distance from the origin have different shapes for different norms:



# DEMO Vectors in Matlab

```
>> x = [ 1 -1 0 ]
```

```
x= 1 -1 0
```

```
>> y = [ 1; -1; 0 ]
```

```
y =
```

```
1
```

```
-1
```

```
0
```

```
>>
```

# DEMO Matrices in Matlab

```
>> A = [ 1 -1 0; 1 2 3; 3 -1 2 ]
```

```
A=
```

```
    1    -1     0
    1     2     3
    3    -1     2
```

```
>> A*y
```

```
ans =
```

```
    2
   -1
    4
```

```
>>
```

# DEMO Accessing elements

```
>> A = [ 1 -1 0; 1 2 3; 3 -1 2 ];  
>> A(1,1)  
ans =  
    1  
>> A(1)  
ans =  
    1  
>> A(1,:)   
ans =  
    1 -1 0
```

# DEMO Accessing elements

```
>> A = [ 1 -1 0; 1 2 3; 3 -1 2 ];
```

```
>> A(:,1)
```

```
ans =
```

```
1
```

```
1
```

```
3
```

```
>> A(2:3,1)
```

```
ans =
```

```
1
```

```
3
```

# DEMO Transposition

```
>> A = [ 1 -1 0; 1 2 3; 3 -1 2 ]
```

```
A =
```

```
    1    -1     0
```

```
    1     2     3
```

```
    3    -1     2
```

```
>> A'
```

```
ans =
```

```
    1     1     3
```

```
   -1     2    -1
```

```
    0     3     2
```

```
>>
```

# DEMO Scalar product

```
>> x= [ 0; 1; 2 ]
```

```
x=
```

```
0
```

```
1
```

```
2
```

```
>> y= [ 2; 0; -1 ]
```

```
y=
```

```
2
```

```
0
```

```
-1
```

```
>> x' * y
```

```
ans =
```

```
-2
```



# DEMO Errors

- If you try to use the value of an element outside of a matrix, it is an error:

```
>> A = [ 1 -1 0; 1 2 3; 3 -1 2 ]
A=
     1     -1     0
     1      2      3
     3     -1      2

>> t=A(4,5)

Index exceeds matrix dimensions
```

- On the other hand, if you store a value in an element outside of the matrix, the size increases to accommodate the newcomer. Other created spaces are filled with 0.

# DEMO Colon operator

- The colon operator, `:`, is one of MATLAB's most important operators. It occurs in several different forms. The expression `1:10` is a row vector containing the integers from 1 to 10

```
>> 1:10  
  
ans =  
    1    2    3    4    5    6    7    8    9   10
```

- To obtain non unit spacing, specify an increment. For example:

```
>> 100:-7:50  
  
ans =  
   100   93   86   79   72   65   58   51
```

# DEMO Built-in functions

- MATLAB provides five functions that generate basic matrices:
  - `zeros` – all zeros
  - `ones` – all ones
  - `rand` – uniformly distributed random elements
  - `randn` – normally distributed random elements
  - `eye` – identity matrix
- Some examples:

```
>> F=5*ones(3,3)
```

```
F =  
 5 5 5  
 5 5 5  
 5 5 5
```

```
>> R=randn(4,4)
```

```
R =  
 1.0668  0.2944 -0.6918 -1.4410  
 0.0593 -1.3362  0.8580  0.5711  
 -0.0956  0.7143  1.2540 -0.3999  
 -0.8323  1.6236 -1.5937  0.6900
```

# DEMO MATLAB files and programs

- For example, create a file called factbar.m that contains these MATLAB commands:

```
% investigate the factorial explosion

r=ones(1,6);
for n=2:6
    r(n)=n*(r(n-1));
end;
bar(r);
```

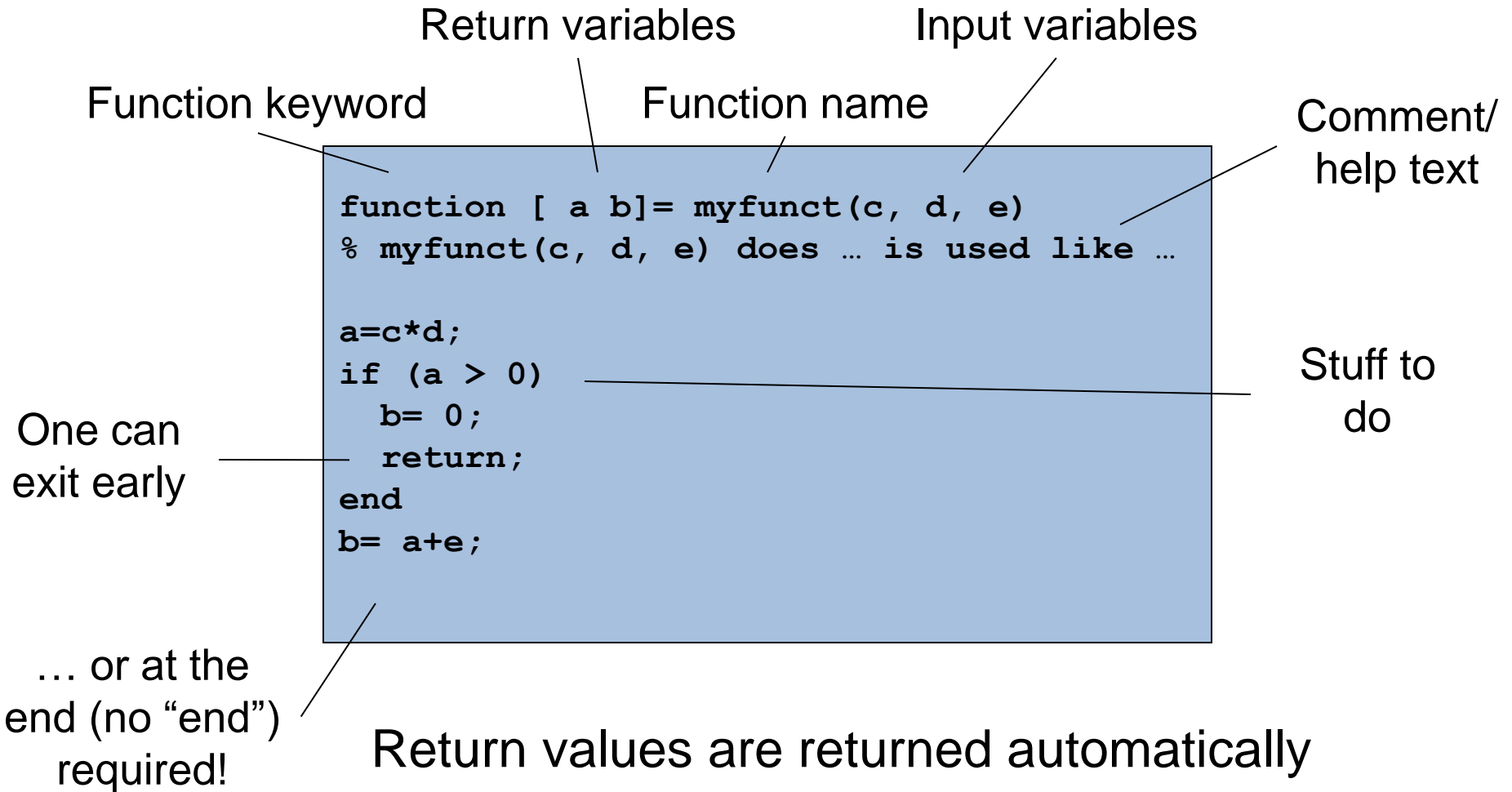
- This is a **script** (rather than a **function**) because it doesn't take any inputs or give any outputs.

# DEMO M-file functions

- **Functions** are M-files that can accept input arguments and return output arguments; the name of the M-file and the function should be the same (**WARNING: If they are not the same, the file name overrides!**).
- Functions operate on variables within their own workspace

```
function f=myfact(n)
% MYFACT(N) computes N! using an iterative method
f=1;
if (n>1)
    for m=2:n
        f=m*f;
    end;
elseif (n<0)
    error('negative factorial attempted');
end;
```

# M-file functions



# Calling your own functions

```
function [ a b]= myfunct(c, d, e)
...
end;
```

myfunct.m

```
>> [ apple orange] = myfunct(candy, d, e);
```

If you do not provide multiple variables for return values, only one of the return values will be considered (and goes into “ans”)

# A bit more detail ...

- Variables in Matlab are passed by value, i.e. the content of the variables outside the function remains unchanged

```
function [ a b]= myfunct(c, d, e)
    e= 5;
    ...
end;
```

```
>> e= 2;
>> [ apple orange] = myfunct(candy, d, e);
>> e
e=
    2
```



# Example: visualising matrix action

“testMatrixSphere.m” draws a sphere and applies a matrix to it repeatedly

```
>> a= 0.2
>> A= [ cos(a)  sin(a)  0;
        -sin(a)  cos(a)  0;
         0       0       1]
>> B= [ 0       0       1;
        0  cos(a)  sin(a);
        0 -sin(a)  cos(a)]
>> testMatrixSphere(A,10);
>> testMatrixSphere(B,10);
>> testMatrixSphere(A*B,10);
```

# File management

- MATLAB uses a search path, or a list of directories, to determine how to execute functions. When we call a standard function, MATLAB executes the first M-file on the path that has the specified name.
- We can override this behaviour using special private directories and sub-functions. The command `path` shows the search path on any platform.
- MATLAB provides several generic operating system commands for manipulating and managing files:

# File management

<b>Command</b>	<b>Description</b>
<code>what</code>	Return a listing of all M-files in the current directory of folder
<code>dir</code>	List all files in the current directory or folder
<code>ls</code>	Same as <code>dir</code>
<code>type test</code>	Display the M-file <code>test.m</code> in the command window
<code>delete test</code>	Delete the M-file <code>test.m</code>
<code>cd path</code>	Change to directory of folder given by <code>path</code>
<code>chdir path</code>	Same as <code>cd path</code>
<code>cd</code>	Show present working directory or folder (unlike UNIX)
<code>chdir</code>	Same as <code>cd</code>
<code>pwd</code>	Same as <code>cd</code>
<code>which test</code>	Display the directory path to <code>test.m</code>

# “Toolboxes”

- Functions and scripts can call each other
- A collection of functions/scripts in a directory can form a complex, large program (much like a java `.jar` library)
- Existing toolboxes are such libraries

# Alternatives to Matlab

- Python (numpy, scipy and matplotlib)
- Octave
- Mathematica