## Estimating Labels

 from Label ProportionsStatistical Machine Learning - NICTA , Australian National University, Stanford University


#### Abstract

Consider the following problem: given sets of unlabeled observations, each set with known label proportions, predict the labels of another set of observations, also with known label proportions. This problem appears in areas like e-commerce, spam filtering and improper content detection. We present consistent estimators which can reconstruct the correct labels with high probability in a uniform convergence sense. Experiments show that our method works well in practice.


## Problem Statement

Assume you want to entice customers to purchase a product. You have the choice of handing out a coupon to entice users to buy. It is your goal to determine who should be sent a coupon to encourage a purchase and who would buy the product regardless. However, the only information available is the set of customers which purchased the product when no discount was offered, and another (independent) set of customers which purchased the product with the discount, without explicit information as to whether they would have made the purchase if the discount had not been offered.

(Formal) problem formulation:
Given

- $n$ sets of datasets $X_{i}=\left\{x_{1}^{i}, \ldots, x_{m_{i}}^{i}\right\}$ of respective sample sizes $m_{i}$ as calibration sets
- a set $X=\left\{x_{1}, \ldots, x_{m}\right\}$ as a test set
- fractions $\pi_{i y}$ of patterns of labels $y \in \mathcal{Y}(|\mathcal{Y}| \leq n)$ contained in each set $X_{i}$
- marginal probability $p(y)$ of the test set $X$

Find

- conditional class probability estimates $p(y \mid x)$


## Gaussian Process Solution

- Conditional exponential likelihood model

$$
\begin{aligned}
p(y \mid x, \theta) & =\exp (\langle\phi(x, y), \theta\rangle-g(\theta \mid x)) \text { with } \\
g(\theta \mid x) & =\log \sum_{y \in \mathcal{Y}} \exp \langle\phi(x, y), \theta\rangle
\end{aligned}
$$

- Gaussian prior

$$
-\log p(\theta) \propto \lambda\|\theta\|^{2}
$$

- Posterior

$$
-\log p(Y \mid X, \theta) p(\theta)=\sum_{i=1}^{m}\left[g\left(\theta \mid x_{i}\right)-\left\langle\phi\left(x_{i}, y_{i}\right), \theta\right\rangle\right]+\lambda\|\theta\|^{2}
$$

- Convex optimization problem

$$
\begin{gathered}
\theta^{*}=\underset{\theta}{\operatorname{argmin}}\left[\sum_{i=1}^{m} g\left(\theta \mid x_{i}\right)-m\left\langle\mu_{X Y}, \theta\right\rangle+\lambda\|\theta\|^{2}\right] \text { with } \\
\mu_{X Y}:=\frac{1}{m} \sum_{i=1}^{m} \phi\left(x_{i}, y_{i}\right)
\end{gathered}
$$

However, we do not have $y_{i}$, label for each observation.
Re-calibration of Sufficient Statistics - Intuition Convergence of empirical means:


Same procedure applies for multiclass setting .

## Performance Guaranteed!

- Bound on the mean operator

With probability $1-\delta$ the following bound holds:

$$
\begin{aligned}
& \left\|\mu_{X Y}-\hat{\mu}_{X Y}\right\| \leq[2+\sqrt{\log ((n+1) / \delta)}] \times \\
& {\left[m^{-\frac{1}{2}}+\left[\sum_{i, j} m_{i}^{-\frac{1}{2}} m_{j}^{-\frac{1}{2}}\left|\left[\pi^{-1}\right]^{\top} K^{y, p} \pi^{-1}\right|_{i j}\right]^{\frac{1}{2}}\right]}
\end{aligned}
$$

For binary classification, the bound simplifies to

$$
\left\|\hat{\mu}_{X Y}-\mu_{X Y}\right\| \leq 2 \rho[2+\sqrt{\log 2 / \delta}]\left[m_{1}^{-\frac{1}{2}}+m_{+}^{-\frac{1}{2}}\right]
$$

- Bound on the minimizer of the log-posterior (Altun \& Smola 2006)

$$
\left\|\theta^{*}-\hat{\theta}^{*}\right\| \leq \lambda^{-1}\|\mu-\hat{\mu}\|
$$

- Bound on the log-posterior (Altun \& Smola 2006)

$$
L\left(\hat{\theta}^{*}, \hat{\mu}\right)-L\left(\theta^{*}, \mu\right) \leq\left\|\hat{\theta}^{*}-\theta^{*}\right\|\|\hat{\mu}-\mu\|=\lambda^{-1}\|\mu-\hat{\mu}\|^{2}
$$

## Alternative Solutions

- Reduction to binary (DS)
- a binary classifier between set $X_{1}$ and $X_{2}$
- label thresholding according to the known proportions
- Density estimation (KDE)
- density estimation for each dataset $X_{i}$
- re-calibration to get $p(x \mid y)$ via $\sum_{i}\left[\pi^{-1}\right]_{y i} p(x, y \mid i)$
- finally invoke Bayes' theorem to compute posterior probabilities.
- MCMC (Kück \& de Freitas 2005)
- explicitly generate mixing proportions per group by hierarchical probabilistic graphical model
- use sampling to generate samples of model posterior distribution


## Experiments

- Binary

-3-class

| Data | Mean Map | KDE | DS | MCMC | BA |
| :--- | :--- | :---: | :---: | :---: | :---: |
| protein A | $44.6 \pm 0.3$ | $60.2 \pm 0.1$ | N/A | $65.3 \pm 1.9$ | 61.2 |
| protein B | $45.7 \pm 0.6$ | $61.2 \pm 0.0$ | N/A | $67.7 \pm 1.8$ | 61.2 |
| dna A | $16.6 \pm 1.0$ | $30.7 \pm 0.8$ | N/A | $37.7 \pm 0.8$ | 40.5 |
| dna B | $29.1 \pm 1.0$ | $33.0 \pm 0.7$ | N/A | $40.5 \pm 0.0$ | 40.5 |
| senseit A | $19.8 \pm 0.1$ | $43.1 \pm 0.0$ | N/A | $\ddagger$ | 43.2 |
| senseit B | $21.0 \pm 0.1$ | $43.1 \pm 0.0$ | N/A | $\ddagger$ | 43.2 |

$\ddagger$ : Program as implemented fails (large datasets)

## Extensions

- Entropy and regularization :
choosing various Csiszar and Bregman distances will produce a range of diverse estimators
- Function space :
measuring the deviation in moment matching in term of $\ell_{\infty}$ norm recovers sparse coding $\ell_{1}$ (dual connection)


## Summary

- A new problem formulation and quite relevant in many aspects
- Our estimator can be easily implemented
- Our estimator enjoys the same rates of convergence as what can be expected from building an estimator with a fully labeled sample
- Our solution can be easily extended to other learning frameworks
- Our estimator works well in practice!

